

Voice coil actuator Type 820



Voice coil actuator - Type 820

Characteristics and features

- optimized magnetic flux
- precisely adjustable operating force over the entire stroke range
- precise and highly dynamic positioning drive in conjuction with encoder and controller
- oscillating drive with adjustable force and frequency
- integrated bearing of coil assembly
- nearly hysteresis-free
- minimum emission
- plug-and-play design
- wide range of forces, strokes and dimensions available
- we can provide advice about the electric control at any time
- additional electric control and sensors for a complete solution if required

Mönninghoff power transmission represents an infinite variant diversity that is applied by all areas of modern mechanical engineering.

Our technologies are designed to operate under extreme conditions. We offer high precision products for medical robotics, fail-proof security for aerospace technology or synchronization soultions for the packaging or printing industry.

We thus address customers who have the highest standards for their own machines or systems. To them, we can offer highly complex, application-specific solutions.

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Match code

Mönninghoff voice coil actuators are indicated by the following match code:



820 . A . B . C

- A size of actuator
- B design of coil
- C design of magnet holder

Choosing the suitable voice coil actuator is highly dependent on the movement and force demands of the application.

Our engineers can assist in finding an application-specific solution at any time. Together, we can develop individual and innovative solutions for extreme operating conditions.

Ordering example

Mönninghoff voice coil actuator Type 820.13.1.1

design of coil design of magnet holder guided with two coil windings



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Size of actuator

When dimensioning a Mönninghoff voice coil actuator, several technical preconditions should be considered:

• The sum of the application specific forces, for example the acceleration force or the weight force, must be smaller than the nominal force of the actuator



 Calculations are based on 20 °C environmental temperature and 150 °C coil temperature while the steady magnet is attached to a massive metal plate. In case of different mounting conditions, it is important to monitor the coil temperature, which is not allowed to exceed 150 °C

Requirement $T_{MaxSP} \le 150^{\circ}C$

Design of the actuator



Type 1.1, coil guided with two coil windings **high axial force**



Type 2.1, coil not guided with two coil windings **high axial force**



Type 3.2, coil not guided with single coil winding **large stroke**

| F _N | nominal force of actuator [N] |
|----------------|---|
| F _G | = weight force [N] |
| F _A | = acceleration force [N] |
| TMAXSP | = maximum coil temperature [°C] |



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Size of actuator



Types 1.1, 2.1 and 3.2 identical in outer dimensions and mounting dimensions

Technical data

| Size | | | | 05 | | | 13 | |
|-----------------------------------|------------------|-----------|----------------|----------------|----------------|----------------|----------------|----------------|
| Туре | | | 1.1 | 2.1 | 3.2 | 1.1 | 2.1 | 3.2 |
| guidance | | | internal | - | - | internal | - | - |
| stroke | Н | [mm] | 5 | 5 | 15 | 5 | 5 | 20 |
| nominal force | F_{N} | [N] | 8,0 | 8,0 | 3,9 | 33 | 33 | 12,5 |
| current at nominal force | I _N | [A] | 2,2 | 2,2 | 1,9 | 3,1 | 3,1 | 2,2 |
| max. input power at nominal force | Pnmax | [W] | 19,6 | 19,6 | 15,2 | 39,0 | 39,0 | 21,6 |
| DC resistance at 20°C | R ₂₀ | [Ω] | 2,68 | 2,68 | 2,79 | 2,69 | 2,69 | 2,96 |
| DC resistance at 150°C | R ₁₅₀ | [Ω] | 4,04 | 4,04 | 4,21 | 4,06 | 4,06 | 4,47 |
| thermal resistance | $R_{_{th}}$ | [°C/W] | 6,6 | 6,6 | 8,6 | 3,3 | 3,3 | 6,0 |
| inductance | L | [mH] | 0,34 | 0,34 | 0,56 | 0,58 | 0,58 | 0,90 |
| force constant | K_{FI} | [N/A] | 3,64 | 3,64 | 2,05 | 10,65 | 10,65 | 4,03 |
| Back EMF constant | K_{ind} | [V/(m/s]] | 8,45 | 8,45 | 4,03 | 17,25 | 17,25 | 10,38 |
| electrical time constant | $T_{_{el}}$ | [µs] | 127 | 127 | 201 | 216 | 216 | 304 |
| mechanical time constant | T _{me} | [ms] | 2,18 | 2,01 | 7,42 | 1,27 | 1,20 | 5,26 |
| coil mass | m ₅ _₽ | [g] | 25 | 23 | 22 | 87 | 82 | 78 |
| total mass | m _{ges} | [g] | 133 | 131 | 128 | 600 | 595 | 585 |
| dimensions | D | [mm] | 30 | 30 | 30 | 50 | 50 | 50 |
| | D ₁ | | 24,6 | 24,6 | 24,6 | 42 | 42 | 42 |
| | d ₁ | | 14 2 x 180° | 14 2 x 180° | 14 2 x 180° | 25 3 x 120° | 25 3 x 120° | 25 3 x 120° |
| | d₂ | | MЗ | МЗ | MЗ | M4 | M4 | M4 |
| | d ₃ | | 22 2 x 180° | 22 2 x 180° | 22 2 x 180° | 35 3 x 120° | 35 3 x 120° | 35 3 x 120° |
| → III ← Ø5.5 ▲ | d ₄ | | M3 | MЗ | MЗ | M4 | M4 | M4 |
| - 20- | L | | 42,5 | 42,5 | 42,5 | 62 | 62 | 62 |
| | l ₂ | | 34,3 | 34,3 | 34,3 | 51 | 51 | 51 |
| | l ₃ | | 6 | 6 | 6 | 7,5 | 7,5 | 7,5 |
| | I_4 | | 5 | 5 | 5 | 8 | 8 | 8 |
| | | | | | | | | |

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Size of actuator



Types 1.1, 2.1 and 3.2 identical in outer dimensions and mounting dimensions

Technical data

| Size | | | | 15 | | | 21 | |
|-----------------------------------|------------------|-----------|----------------|----------------|----------------|----------------|----------------|----------------|
| Туре | | | 1.1 | 2.1 | 3.2 | 1.1 | 2.1 | 3.2 |
| guidance | | | internal | - | - | internal | - | |
| stroke | Н | [mm] | 10 | 10 | 35 | 10 | 10 | 50 |
| nominal force | F_{N} | [N] | 82 | 82 | 28 | 163 | 163 | 56 |
| current at nominal force | I _N | [A] | 4,2 | 4,2 | 2,6 | 4,1 | 4,1 | 2,1 |
| max. input power at nominal force | Pnmax | [W] | 66,3 | 66,3 | 28,7 | 88,8 | 88,8 | 39,1 |
| DC resistance at 20°C | R ₂₀ | [Ω] | 2,49 | 2,49 | 2,81 | 3,5 | 3,5 | 5,87 |
| DC resistance at 150°C | R ₁₅₀ | [Ω] | 3,76 | 3,76 | 4,25 | 5,28 | 5,28 | 39,09 |
| thermal resistance | R _{th} | [°C/W] | 2,0 | 2,0 | 4,5 | 1,5 | 1,5 | 3,6 |
| inductance | L | [mH] | 0,89 | 0,89 | 1,34 | 1,91 | 1,91 | 3,94 |
| force constant | K _{FI} | [N/A] | 19,52 | 19,52 | 10,77 | 39,76 | 39,76 | 26,67 |
| Back EMF constant | K_{ind} | [V/(m/s)] | 25,6 | 25,6 | 18,1 | 29,2 | 29,2 | 48,4 |
| electrical time constant | T _{el} | [µs] | 357,4 | 357,4 | 476,9 | 546 | 546 | 671 |
| mechanical time constant | T_{me} | [ms] | 1,03 | 0,99 | 2,88 | 1,27 | 1,21 | 2,32 |
| coil mass | m _{sp} | [g] | 207 | 198 | 200 | 420 | 400 | 510 |
| total mass | m _{ges} | [g] | 1780 | 1771 | 1773 | 3980 | 3960 | 4070 |
| dimensions | D | [mm] | 70 | 70 | 70 | 90 | 90 | 90 |
| | D ₁ | | 60 | 60 | 60 | 78 | 78 | 78 |
| | d1 | | 30 3 x 120° | 30 3 x 120° | 30 3 x 120° | 40 3 x 120° | 40 3 x 120° | 40 3 x 120° |
| x x | d₂ | | M5 | M5 | M5 | M6 | M6 | M6 |
| | d ₃ | | 55 3 x 120° | 55 3 x 120° | 55 3 x 120° | 70 3 x 120° | 70 3 x 120° | 70 3 x 120° |
| → [] < Ø5,5 ↑ | d_4 | | M5 | M5 | M5 | M6 | M6 | M6 |
| + 20 | L | | 86,5 | 86,5 | 86,5 | 112 | 112 | 112 |
| | l ₂ | | 75 | 75 | 75 | 98,3 | 98,3 | 98,3 |
| | l ₃ | | 8 | 8 | 8 | 9,7 | 9,7 | 9,7 |
| | I_4 | | 17 | 17 | 17 | 12 | 12 | 12 |

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Force / stroke characteristics



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System solutions

You need more?

Mönninghoff clutches can be combined with a variety of many other power transmission elements. Such complex high-tech systems can solve any application-specific tasks and can fulfill any customer-specific wishes.



In many cases, a combination of different drive elements is needed to solve the applications particular problems and difficulties. Being not just supplier but technological partner to our customers, our extensive engineering is part of extraordinary and challenging power transmission projects.



Our product is the know-how, with hardware as an added bonus.

Driven by excellence

Why Mönninghoff

- intensive dialog with our customers' engineers
- decades of experience and competence
- deep understanding for all areas of mechanical engineering
- highly modern and flexible machine park
- enthusiasm for quality
- flexibility, inventiveness and communication skills of our employees
- commitment to Germany and Bochum as industrial location

How to reach us

Sales

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Order Management confirmation@moenninghoff.de +49 2327 3033-353



For the competent processing and smooth handling of your orders and delivery dates.

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